# **Mobile Communications**

# DC REMOTE CONTROL BOARD

19A704686P3

(2-Frequency Transmit and Receive with Channel Guard)

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LINE TERMINATING IMPEDANCE	600 ohms
LINE LOOP IMPEDANCE (MAXIMUM)	11,000 ohms (8000 line and 3000 matching)
INPUT VOLTAGE	+10 Volts DC $\pm 0.5$ Volts
CURRENT (standby & transmit)	50 milliamperes maximum
LINE LEVEL (Line to Transmitter)	-20 to +11 dBm
OUTPUT LEVELS Transmit Receive	10-200 millivolts (adjustable) -20 to +7 dBm
DISTORTION (300-1000-3000 Hz) Transmit Receive	Less than 3% Less than 5%
FREQUENCY RESPONSE	+1, -3 dB with 6 dB/octave from 300 to 3000 Hz
TEMPERATURE RANGE	-30°C to +75°C (-22°F to +153°F)

<sup>\*</sup> These specifications are intended primarily for the use of the serviceman. Refer to the appropriate Specification Sheet for the complete specifications.

### DESCRIPTION

PC remote control board 19A704686P3 is used in remote and local/remote station combinations to provide one and two-frequency with Channel Guard disable (monitor). The DC remote control board provides the interface between a remote control console and the base station.

Connections to the remote control console are made at J1 on the DC remote control board. Station connections are made at J2 and J3. Supply voltage for the DC remote board is taken from the station regulated +10 Volts. Frequency selection is available in wall-mount (remote only) stations.

### DC CONTROL FUNCTIONS

The DC remote control board provides up to six remote control functions by the application of different current levels and polarities to select each function. The different control currents and functions are shown in Table I.

### TELEPHONE LINE CHARACTERISTICS

The telephone lines used in this DC remote control application requires one metallic pair for both audio and control voltages, with the control voltage simplexed from line to line. To obtain the most satisfactory service over this telephone link, some general knowledge of the capability of these lines is required.

A telephone pair is simply a pair of wires, normally ranging from AWG #19 to AWG #26 in size. These wires, furnished by the local telephone company, pass through overhead cables, underground cables, through junction points, and switchboards. To the user, however, they may be considered a simple pair of wires.

Equipment that is designed to operate with such a pair should have nominal impedance of 600 ohms. A telephone pair will normally have a maximum length of about 12 miles before amplification is added by the telephone company to make up for line losses. There is an inherent loss in any telephone line installation due to the series inductance and resistance and the shunt capacitance of the wires.

This loss is a direct function of the length of the line, and varies with the wire size used. As an example, with AWG #19 wire, a distance of six miles may be covered before one-half the input voltage of a 1000 Hz tone is lost. With AWG #26 wire, only two and one-quarter miles may be covered before one-half the input voltage is lost. Line losses as high as 30 dB can be tolerated in operating a transmitter from the remote but such high losses should be avoided whenever possible. Although the telephone pair is fairly well balanced, some noise will be induced into the line, especially if an unshielded run has to be made in a florescent-lighted building.

The DC resistance of any telephone pair will affect the control circuits between the Controller and the base station. Current regulators incorporated in the Remote Control minimize these variations after initial adjustment. The Remote operates with a total control line loop resistance as great as 11,000 ohms. There is a possibility, however, that stray currents, due to leakage, noise, faults, earth currents, etc., may cause faulty operation.

After the telephone line has been connected, refer to the Adjustment Procedure for setting the input and output line levels. These adjustments are required before the station is put in operation.

TABLE I - Control Current and Function Chart (Remote Only)

			CONTROL C	URRENT IN	MILLIAMPE	RES
FUNCTION	-11	-6	-2.5	0	+6	+11
1 or 2 Freq. Transmit 1 Freq. Receive/CG Monitor			Receive F1 With CG Disable	Receive F1	Transmit F1	Transmit F2
1 or 2 Freq. Transmit 2 Freq. Receive/CG Monitor	Receive F2 With CG Disable	Receive F2	Receive F1 With CG Disable	Receive F1	Transmit F1	Transmit F2
1 Freq. Transmit 1 Freq. Receive/CG Monitor			Receive F1 With CG Disable	Receive F1	Transmit F1	

### CIRCUIT ANALYSIS

Remote control board 19A7C4686P3 provides a maximum of three remote control functions. These functions are two frequency transmitter keying, two frequency receive, and Channel Guard disable (channel monitoring). The remote control board also provides the audio paths for transmit and receive audio.

The remote control board consists of four optocouplers (U5 through U8), two operational amplifiers (U2 and U4), a quad-comparator and a 32 X 8 PROM.

### TRANSMIT AUDIO

Transmit audio combined with the control current from the remote console is applied to the remote control board at J1-1 and J1-4. Capacitors C1 and C2 block the control currents while passing the audio to transformer T1. The transformer output is coupled through potentiometer R1 to the input of op-amp U4-6. R1 is also used as the feedback resistor across the op-amp. The amplified output at U4-7 is applied to the station transmitter through J2-1 (MIC AUDIO).

### RECEIVE AUDIO

Receive audio from the station receiver is applied to the remote control board at J2-9 (RX AUDIO). The audio at J2-9 is coupled through a low-pass filter (R16 and C14) which provides 6 dB/octave de-emphasis. The filter output is applied to pre-amplifier U4-3.

Pre-amplified audio from U4-1 is coupled through bilateral switch U3-1 and -2, and applied to the line driver stages consisting of both sections of op-amp U2. R2 is the level control for the receive audio.

Bilateral switch U3 is controlled by the RUS line from the station. When the RUS line goes high (station receiver unsquelches), U3-13 goes high, turning on U3. This couples the audio output of the pre-amp stage to the line drivers. When the RUS line is low, (receiver squelched) U3 is turned off.

Remote line amplifiers U2 can drive the control line to a level of +7 dBm when the line is terminated into 600 ohms. However, removing the jumper from U2-8 and connecting pin 8 to 13 Volts DC will provide an output of over +11 dBm, if required. The output of U2 is coupled through T1 to the control pair at J1-1 and J1-4.

### CONTROL CURRENT

The four optocouplers (U5, U6, U7 and U8) are used for current detection and line isolation. Each optocoupler contains a Light Emitting Diode (LED), and a phototransistor serving as a light detector. When a DC current of the correct polarity is applied to pin 1, the LED conducts and emits light. This light turns on the phototransistor, coupling the input current to the output of the phototransistor (see Figure 1).

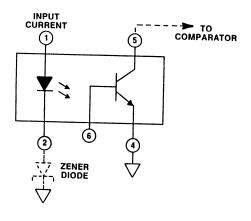


Figure 1 - Simplified Optocoupler Circuit

When zero current is on the control pair (J1-1 and J1-4), all four optocoupler LED's are off, keeping all four phototransistors off. When the phototransistors are off, pin 5 of each optocoupler is pulled up to 5 Volts DC through pull-up resistors, R19,R22,R25 and R28. The +5 Volts are applied to the inputs on quad-comparator U10 pins 5,7,9 and 11. A reference voltage for comparator U10 is provided by voltage dividers R33 and R34, which applies a reference voltage of 1.2 Volts.

Whenever the inputs to U10 are higher than the reference voltage, the outputs at U10-1, -2, -13 and -14 go high (+5 Volts). The open collector outputs of comparator U10 are coupled to the address lines of PROM U9. The unused address line (pin 14) is tied to ground.

With zero current on the control line, all used PROM address lines are held high. When all PROM inputs are high, outputs 01 and 05 of PROM U9 are held low. This holds the radio in the RX1 mode with Channel Guard (CG) enabled.

Table II shows how the PROM outputs are controlled by the PROM inputs in each of the six possible conditions of the remote control board.

TABLE II - Prom Inputs and Outputs vs Current

### CONDITIONS:

1.	+11	mΑ	 TX2

2. -11 mA ---- RX2 with CG Disable

5. -2.5 mA ---- RX1 with CG Disable

	PROM INPUT							F	ROM OU'I	TPUT	
	11 mA A3	6 mA A2	+ mA A1	- mA AO	=	CG 06	PTT 05	TX2 04	TX1 03	RX2 02	RX1 01
1.	0	0	0	1	=	1	1	0	1	1	1
2.	0	0	1	0	=	0	0	1	1	0	1
3.	1	0	0	1	=	1	1	1	0	1	1
4.	1	0	1	0	=	1	0	1	1	0	1
5.	1	1	1	0	=	0	0	1	1	1	0
6.	1	1	1	1	=	1	0	1	1	1	0

When a current on the control pair is greater than 1 milliampere (mA), polarity optocoupler U5 or U6 will turn on. U5 is used as the negative polarity detector, while U6 is used as the positive polarity detector. For example, if the current was -2.5 mA, phototransistor U5 would turn on, pulling U5-5 low. This would be read by the PROM and would provide outputs to allow the radio to monitor RX1. Also, if less than 4 mA is on the control pair, both Q1 and Q2 turn on. When 4 mA or more is on the control pair, Q2 is the first one to turn off. This is because zener diode D6 will not allow the base of Q2 to become greater than 6.8 Volts. As soon as Q2 turns off, the LED in U7 turns on and causes U7-5 to go low, indicating that there is -6 mA on the control pair (RX2).

Transmitter keying is controlled by U9-5(05). When +11 mA or +6 mA is detected, U9-5 goes high. This turns on Q4 and Q5, which applies a low to J2-4 to key the selected channel.

Channel Guard disable is controlled by U9-6(06). When -11 mA or -2.5 mA are detected, U9-6 goes low to disable the selected receive Channel Guard.

### ADJUSTMENT PROCEDURE

There are two adjustments on the DC remote control board; audio deviation to the transmitter (R1), and receive audio level to the remote control console (R2).

### AUDIO DEVIATION

While receiving a 1000 Hz tone from the remote control console, adjust R1 for  $\pm 4.5$  kHz deviation. This should provide a reading of 70 to 120 millivolts at J2-1.

### RECEIVE AUDIO LEVEL

While receiving a 1000 Hz tone with ±3 kHz deviation that is strong enough to fully quiet the receiver, adjust R2 for 0 dBm across terminals J1-1 and J1-4.

### TROUBLESHOOTING

A complete set of DC voltage readings are provided in this manual to assist in servicing the remote control board. (See Page 5).



Ericsson GE Mobile Communications Inc. Mountain View Road • Lynchburg, Virginia 24502

# TROUBLESHOOTING

# DC VOLTAGE READINGS

# DC CONTROL BOARD 19A704686P3

		···							
METERING	REFERENCE	CONTROL CURRENT (MILLIAMPERES)							
POINT		-11 mA	-6 mA	-2.5 mA	O mA	+6 mA	+11 mA		
Q1-E	D3 ANODE	12.75	8.15	3.76	0	8.28	12.77		
-В		11.5	8.84	4.42	.31	8.97	11.48		
-c		13.9	8.25	3.88	.07	8.38	13.91		
Q2-E		13.9	8.25	3.88	.07	8.38	13.91		
-в		6.46	6.44	4.52	.3	6.43	6.46		
-c		15	9.37	3.99	.31	9.49	15.05		
U2-1	GROUND	5	5	5	5	5	5		
-2		5	5	5	5	5	5		
-3		5	5	5	5	5	5		
-4		0	0	0	0	0	0		
-5		5	5	5	5	5	5		
-6		5	5	5	5	5	5		
-7		5	5	5	5	5	5		
-8		10	10	10	10	10	10		
U3-1		0	0	0	0	0	0		
-2		5	5	5	5	5	5		
-7		0	0	0	0	0	0		
-13		10*	10*	10*	10*	0	0		
-14		10	10	10	10	10	10		
U4-1		5	5	5	5	5	5		
-2		5	5	5	5	5	5		
-3		5	5	5	5	5	5		
-4		0	0	0	0	0	0		
-5		5	5	5	5	5	5		

# TROUBLESHOOTING

METERING	REFERENCE			CONTROL CURRENT (MILLIAMPERES)					
POINT		-11 mA	-6 mA	-2.5 mA	O mA	+6 mA	+11 mA		
-6		5	5	5	5	5	5		
-7		5	5	5	5	5	5		
-8		10	10	10	10	10	10		
U5-5		.1	.15	.2	5	5	5		
-6		.6	.6	.6	0	0	0		
U6-5	1	5	5	5	5	.1	.1		
-6		0	0	0	0	.6	.6		
U7-5		.1	.1	5	5	.1	.1		
-6		.6	.6	0	0	.6	.6		
U8-5		.1	5	5	5	5	.1		
-6		.6	0	0	0	0	.6		
U9-1	1	**	**	0	0	**	**		
-2		0	0	**	**	**	**		
-3		**	**	**	**	0	**		
-4		**	**	**	**	**	0		
<b>-</b> 5		.1	.1	.1	.1	4.8	4.8		
-6		0	5	0	5	5	5		
-10		0	0	0	5	5	5		
-11		5	5	5	5	0	0		
-12		0	0	5	5	0	0		
-13		0	5	5	5	5	0		
-16		5	5	5	5	5	5		
U10-1		5	5	5	5	0	0		
-2		0	0	0	5	5	5		
-3		0	0	0	5	5	5		
-4,6,8,10	1	1.2	1.2	1.2	1.2	1.2	1.2		

# TROUBLESHOOTING

REFERENCE			(M:	NTROL CURI	RENT	
	-11 mA	-6 mA	-2.5 mA	O mA	+6 mA	+11 mA
	.1	5	5	5	5	.1
	0	0	0	0	0	0
	0	5	5	5	5	0
	0	0	5	5	0	0
	REFERENCE	-11 mA .1 0 0	-11 mA -6 mA  .1 5  0 0  0 5	-11 mA -6 mA -2.5 mA  .1 5 5  0 0 0 0  0 5 5	-11 mA -6 mA -2.5 mA 0 mA  .1 5 5 5  0 0 0 0 0  0 5 5 5	-11 mA -6 mA -2.5 mA 0 mA +6 mA  .1 5 5 5 5  0 0 0 0 0 0  0 5 5 5 5

- \* Carrier present in receiver
- \*\* Open collector output is open

PARTS LIST

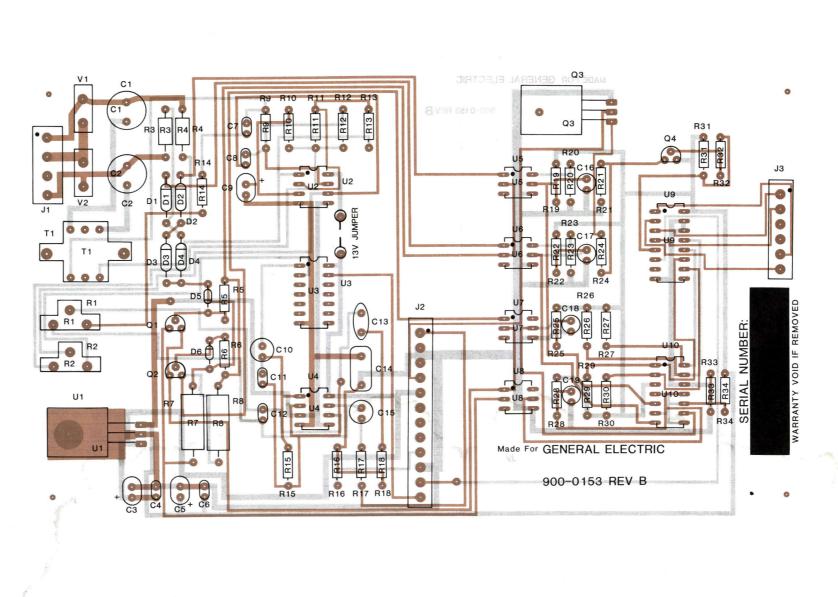
REMOTE CONTROL BOARD 19A704686P3

		ISSUE 2	R18
			R19
SYMBOL	GE PART NO.	DESCRIPTION	R20
3111100	22		R21 and R22
			R23
			R24
C1 and	J19/361-0001	Electrolytic: Non-Polarized, 4 uF.	R25 thru
C2 C3	J19/390-0007	Electrolytic: Tantalum, 10 uF 35 WVDC.	R30
C4	J19/362-0001	Monolithic: .1 uF.	R31
C5	J19/390-0007	Electrolytic: Tantalum, 10 uF 35 WVDC.	R32
C6	J19/362-0001	Monolithic: .1 uF.	R33
C7	J19/361-0003	Electrolytic: Non-Polarized, 1 uF.	4 67
C8	J19/362-0004	Monolithic: 330 pF.	
С9	J19/390-0007	Electrolytic: Tantalum, 10 uF 35 WVDC.	Tl
C10	J19/361-0003	Electrolytic: Non-Polarized, 1 uF.	
Cll and	J19/362-0004	Monolithic: 330 pF.	Ul
C12			U2
C13	J19/362-0002	Monolithic: .47 uF	ш3
C14	J19/380-0011	Mylar: .68 uF	U4
C15	J19/361-0003	Electrolytic: Non-Polarized, 1 uF.	U5
C16 thru C19	J19/360-0004	Electrolytic: 10 uP 16 WVDC.	thur U8
		DIODES	U9 U10
	J19/110-0002	Silicon: sim to 1N4003.	010
D1 thru	313/110-0002	2	
D4	J19/111-0003	Silicon: Zener, 12 v.	VR1 and
D6	J19/111-0012	Silicon: Zener, 6.8 v.	VR2
		JACKS	
	J19/231-0001	Connector: 4 position.	1
J1	J19/231-1066	Connector: 6 position. (2 required).	
J2 J3	J19/231-1066	Connector: 6 position.	1
"		TRANSISTORS	
01	J19/180-0008	Silicon: NPN, sim to MPSA43.	The state of the s
Q1 and	319/100-0000		3
Q2 Q3	J19/180-0007	Silicon: NPN, sim to TIP47.	TO SECOND
Q3	J19/180-0008	Silicon: NPN, sim to MPSA43.	
		RESISTORS	1
7.1	J19/351-0002	Variable: 1 turn, 10 K ohms.	
R1 and R2	013,332 0032		
R3 and	J19/313-0010	22 ohms <u>+</u> 5%, 1/2 w.	
R4 R5	J19/312-0015	22K ohms ±5%, 1/4 w.	
and R6	015, 312 0013		
R7 and R8	J19/315-0022	1.5K ohms <u>+</u> 5%, 2 w.	
R9	J19/312-0045	620 ohms +1%, 1/4 w.	
R10	J19/312-0014	33K ohms ±5%, 1/4 w.	
and R11			
R12	J19/312-0028	470 ohms ±5%, 1/4 w.	
R13	J19/312-0014	33K ohms <u>+</u> 5%, 1/4 w.	
R14	J19/312-0019	1K ohms +5%, 1/4 w.	
*************	DNIENITE ADDED	DELETED OR CHANGED BY PRODUCTION CHANGES	
COMPO	JINEINIO AUDED,	DELETED OR GIANTOED DI PRODUCTION DI MANORE	

	SYMBOL	GE PART NO.	DESCRIPTION
	R15	J19/312-0046	470K ohms ±5%, 1/4 w.
	R16	J19/312-0011	10K ohms +5%, 1/4 w.
	R17	J19/312-0045	620 ohms <u>+</u> 1%, 1/4 w.
	R18	J19/312-0040	4.7K ohms ±5%, 1/4 w.
٦	R19	J19/312-0011	10K ohms ±5%, 1/4 w.
	R20	J19/312-0046	470K ohms +5%, 1/4 w.
1	R21 and R22	J19/312-0011	10K ohms ±5%, 1/4 w.
-	R23	J19/312-0046	470K ohms <u>+</u> 5%, 1/4 w.
	R24	J19/312-0019	1K ohms ±5%, 1/4 w.
	R25 thru R30	J19/312-0011	10K ohms +5%, 1/4 w.
1	R31	J19/312-0040	4.7K ohms +5%, 1/4 w.
	R32	J19/312-0019	1K ohms ±5%, 1/4 w.
	R33	J19/312-0018 J19/312-0015	6.8K ohms ±5%, 1/4 w.  22K ohms ±5%, 1/4 w.
	R34	319/312-0015	TRANSFORMERS
	Tl	J19/410-0003	Coupling: 600 ohms impedance.
			INTEGRATED CIRCUITS
	Ul	J19/130-0022	Linear: 5 Volt Voltage Regulator, sim to UA7805.
	U2	J19/130-0120	Linear: Dual Operational Amplifier, sim to TL062.
-	ū3	J19/130-0067	Digital: Quad Bilateral Switch, sim to 4066.
-	U4	J19/130-0120	Linear: Dual Operational Amplifier, sim to TL062.
	U5 thur U8	J19/130-0097	Linear: Opto-Isolator, sim to 4N36.
- 1	U9	J19/130-0213	Digital: 32 x 8 bit PROM, sim to 74S188.
-	U10	J19/130-0117	Linear: Quad Comparator, sim to LM339.
1			
	VR1 and VR2	J19/300-0001	Varistor.
			MISCELLANEOUS
1		J19/220-0001	Socket: DIP, 16 pin.
		J19/220-0002	Socket: DIP, 14 pin. Socket: DIP, 8 pin.
		J19/220-0003 J19/220-0006	Socket: DIP, 6 pin.
	3	J19/210-0002	Heat Sink: T0220. (Used with U1).
		J19/199-0020	Hex Nut: 6-32. (Used with U1 and Q3).
- 1	3	J19/199-3070	Screw: 6-32 x 1/4. (Used with Ul and Q3).
- 1	3	J19/199-3070	Screw: 6-32 x 1/4. (Used to secure Board).
- 1			Cable Assembly Includes:
	1	J19/231-1052	Connector: 12 position, sim to CE156F22-12.
	1	J19/231-1056	Connector: 12 position, sim to CE156F22-6.
		J19/231-1051	Polarizing Key.
		J19/222-0014	Wire: 22 AWG.
		Stage	
		L.	
		3	
			and the second second
			600
			b.

# **OUTLINE DIAGRAM**

DC Remote Control Board 19A704686P3



(4136-A-04, Rev. B) 4136-A-00, Sh. 1, Rev. B)

RUNS ON SOLDER SIDE

RUNS ON BOTH SIDES

RUNS ON COMPONENT SIDE

